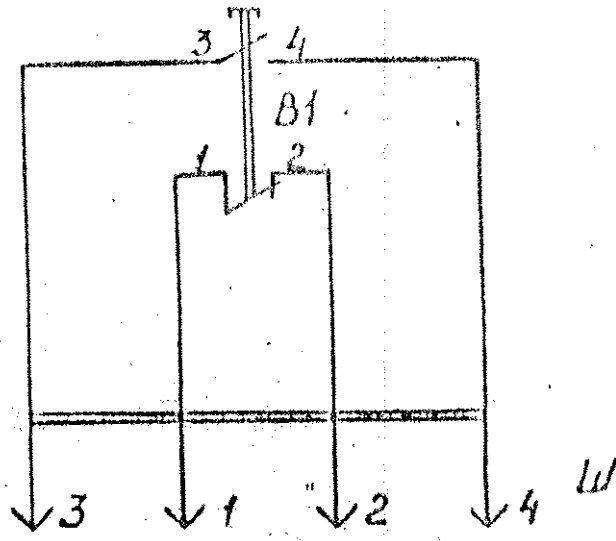


DRAWING NUMBER
D 20 000 33



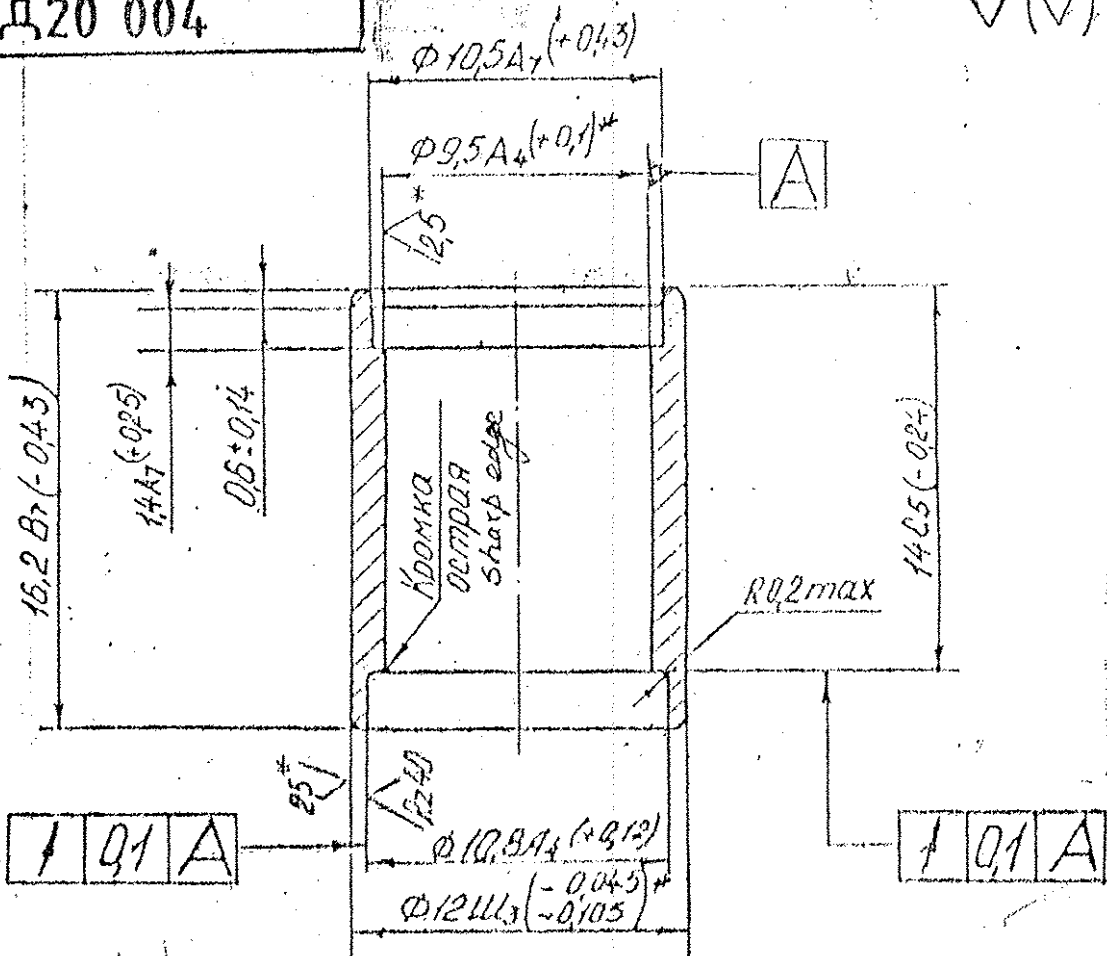
PART No.	NOMENCLATURE	QTY	REMARKS
B1	MICROSWITCH D 301 HO.360.011	1	
W	PLUG WPG20P53W7 ΓEO.364.108TY	1	

PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

		EST. MASS	TO BE STAMPED OR MARKED WHERE INDICATED THIS * (LETTERS)
COPY		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUT-SIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :-	USED ON :- D 20 000 CB
DATE	NATURE OF AMENDMENTS	CONTROLLERATE OF INSPECTION (HEAVY VEHICLES) AVADI	
N	SCALE -	TITLE :- SCHEMATIC CIRCUIT DIAGRAM SENDING UNIT D 20	
D	DIMENSIONS IN mm.		
D	TOLERANCE ON DIMNS UNLESS OTHERWISE STATED.	D S CAT NUMBER	
PD	ALL TIREADS CONFORM TO	DRAWING NUMBER D 20 000 33	
TE	18.2.98		

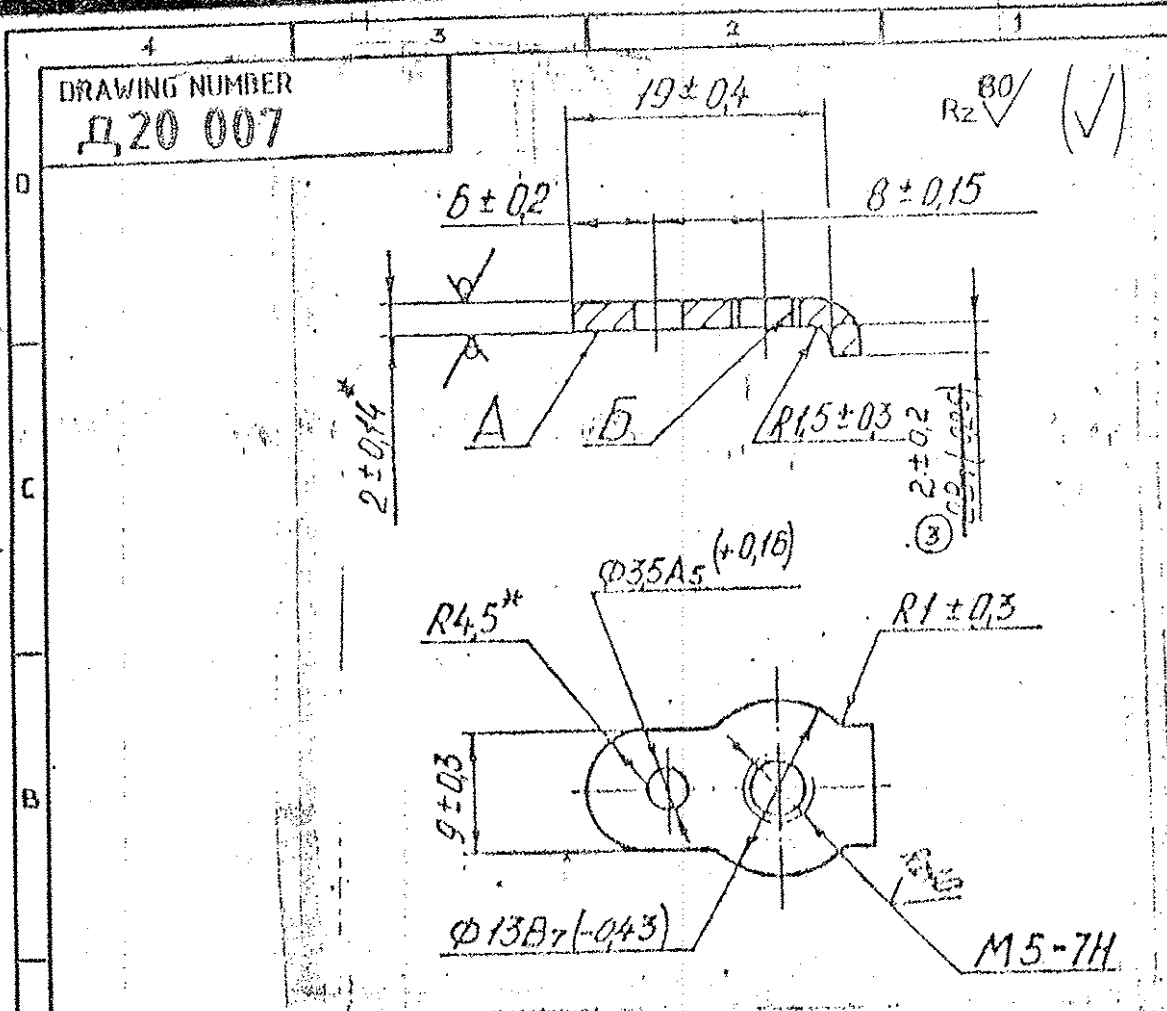
DRAWING NUMBER
A20 004

Rz80 (✓)



- # Dimensions and roughness of surface after coating.
- Coating: Cd9, Chromating.
 ALT. MATL :- C14, IS: 2073-70
 AUTHORITY :- 98704/04/ID-CO-ORD/ALT.COM, APPENDIX 'A' Date 3/5/2005
 PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

		EST. MASS 0.0047	TO BE STAMPED OR MARKED WHERE INDICATED THUS #: (LETTERS)
	MASTER COPY	ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUTSIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :- STEEL 10 GOST 1050-74.	USED ON :- A20 020 CB
JE	DATE	NATURE OF AMENDMENTS	
		SCALE - 4 : 1	
		DIMENSIONS IN mm.	
		TOLERANCE ON DIMNS UNLESS OTHERWISE STATED.	
		ALL THREADS CONFORM TO	
		D S CAT NUMBER	DRAWING NUMBER A20 004

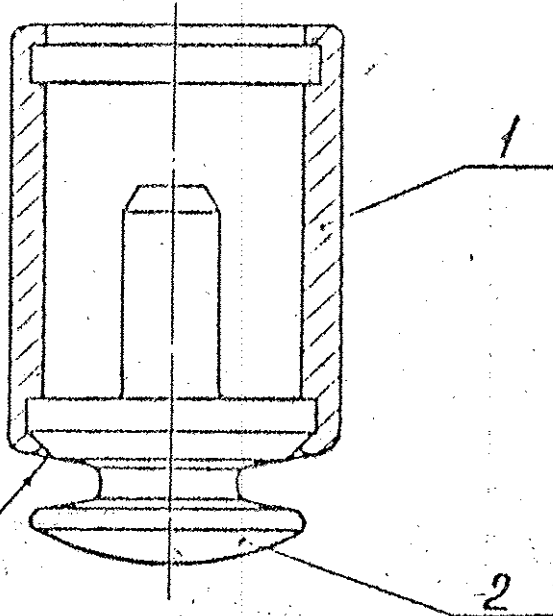


1. * DIMENSIONS FOR REFERENCE.
2. COATING: Zn9, CHROMATING.
3. NON-SQUARENESS OF AXIS OF HOLE b RELATIVE TO SURFACE A SHOULD NOT EXCEED 1°.

PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.
 ALT MATL :- CRSS GRADE 'D' IS: 513-86
 AUTHORITY :- CQA (HV) LETTER NO 98704/04/D-CO-DRD/ALT.COM, DATED: 03/05/2005

		EST. MASS 0.0028	TO BE STAMPED OR MARKED WHERE INDICATED THIS (LETTERS)
MASTER COPY		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUT-SIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :- SHEET. 62 GOST 19904-74 4-11-10 GOST 16523-70	USED ON :- A,20 030 CB
ISSUE	DATE	NATURE OF AMENDMENTS.	
JRN V. Ramon		SCALE - 2:1	
CHO Blasichov		DIMENSIONS IN MM.	
TCD V. Ramon		TOLERANCE ON DIMS UNLESS OTHERWISE STATED.	
APPD S. J.		ALL THREADS CONFORM TO	
DATE 18.2.1987		D S CAT NUMBER	DRAWING NUMBER A,20 007

DRAWING NUMBER
A20 020 CB



To be flared flush

Забальцевать
заподлицо

1. After flaring, the rotation of pin 2 is not allowed.
2. Place of flaring should be coated with lacquer

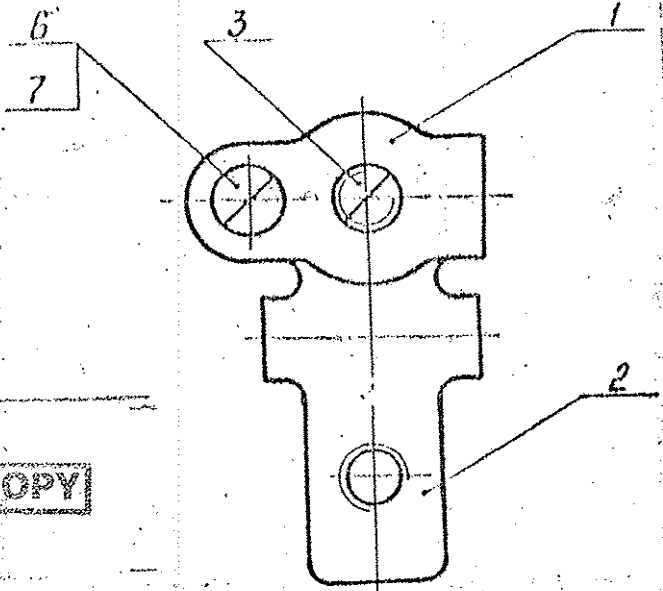
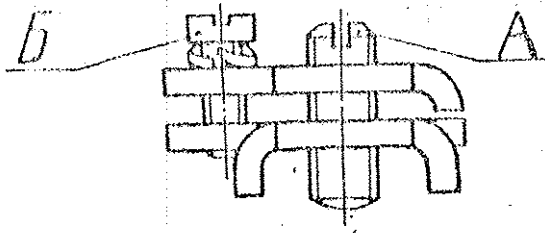
PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

P.
Roy

EST MASS 0.0070		TO BE STAMPED OR MARKED WHERE INDICATED THUS (LETTERS)	
MASTER COPY		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUT- SIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
MATERIAL :-		USED ON :- A20 010 CB	
DATE	NATURE OF AMENDMENTS	CONTROLLERATE OF INSPECTION (HEAVY VEHICLE) AVADI	
SCALE - 4:1	DIMENSIONS IN mm.	ROD ASSY	
TOLERANCE ON DIMNS UNLESS OTHERWISE STATED.	ALL DIMENSIONS UNLESS OTHERWISE STATED.	DRAWING NUMBER A20 020 CB	
8-2-1987			

CE AL

DRAWING NUMBER
D, 20 030 CB



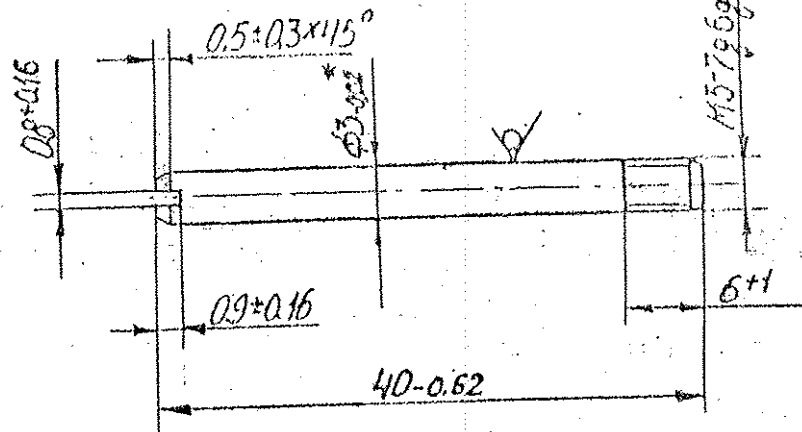
MASTER COPY

1. BAR 1 SHOULD BE SCREWED COMPLETELY ON SCREW A WHICH IS SCREWED IN LEVER.
 2. SCREW B SHOULD BE SCREWED IN. SPRING WASHER SHOULD NOT BE COMPRESSED.
- PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

		EST. MASS 0.0114	TO BE STAMPED OR MARKED WHERE INDICATED THUS # (LETTERS)
		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUTSIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :-	USED ON :-
ISSUE DATE	NATURE OF AMENDMENTS	CONTROLLERATE OF INSPECTION (HEAVY VEHICLES)	
JRN V. Ramani	SCALE - 2 : 1	AVADI	
JRI @hathachug	DIMENSIONS IN mm.	TITLE :- LEVER ASSY	
JCI V. Ramani	TOLERANCE ON DIMS UNLESS OTHERWISE STATED.	D S CAT NUMBER	
APPU	ALL THREADS CONFORM TO	DRAWING NUMBER D20 030 CB	
DATE 18-2-1987			

DRAWING NUMBER
D,74 001

RZ 80 ✓ (✓)



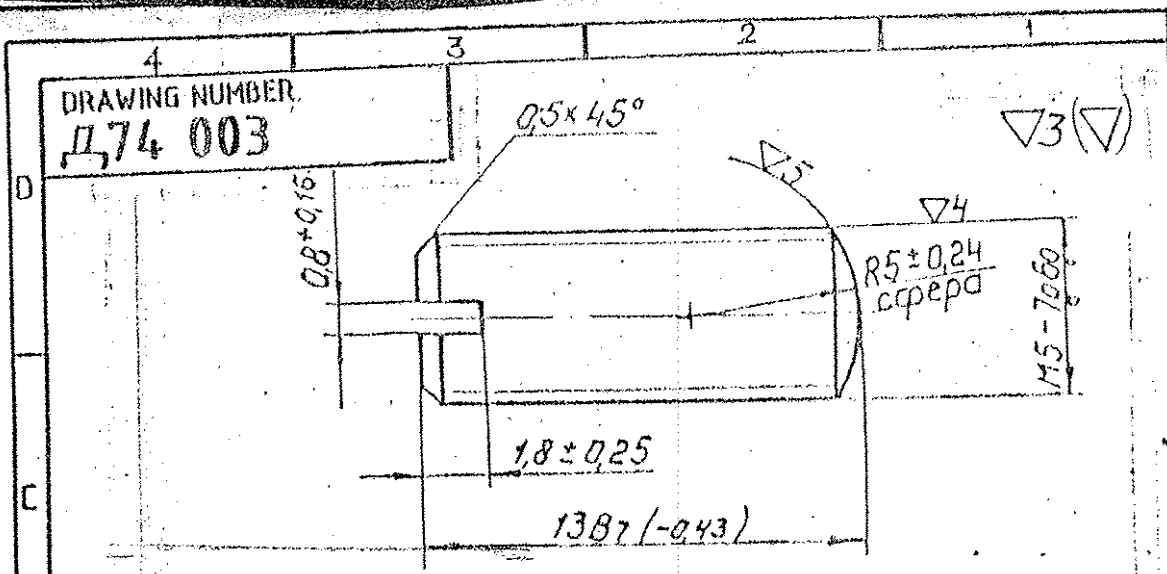
- 1. DIMENSION FOR REFERENCES
- 2. COATING: Zn6, CHROMATIZING.

MASTER COPY

ALT. MATL :- STEEL C40 IS: 1570
 AUTHORITY :- CQA (HV) LETTER NO. 98704/04/D-
 CO-ORD/ALT.COM DATED: 03-05-2005

PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

		EST. MASS 0.0025	TO BE STAMPED OR MARKED WHERE INDICATED THUS * (LETTERS)
		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE N OUT- SIDE N INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :- BAR 3-A-3-y0A GOST 14955-77	USED ON :- 420 000 CB
ISSUE DATE	NATURE OF AMENDMENTS	CONTROLLERATE OF INSPECTION (HEAVY VEHICLES) AVADI	
RN V. Ramani	SCALE - 2 : 1	TITLE :- STUD	
IND A. Lakshmi	DIMENSIONS IN mm.		
CD V. Ramani	TOLERANCE ON DIMNS UNLESS OTHERWISE STATED.	D S CAT NUMBER	
PPD S. S.	ALL THREADS CONFORM TO		
DATE 18.2.1987		DRAWING NUMBER D,74 001	
SIZE AL			



MASTER COPY

1. Допускаемое смещение шлица относительно оси винта 0,3 не более.
2. Термообработка. Палить HRC 30±35.
3. Покрытие Ц9 хр.

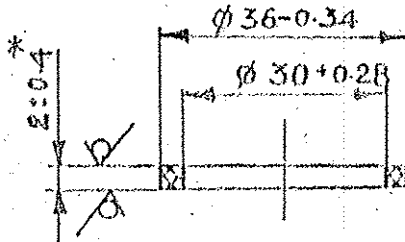
1. Permissible shift of slot relative to axis of screw should not exceed 0.3.
 2. Heat treatment: To be heated to HRC 30±35.
 3. Coating: Zn9, Chromatizing.
- PILOT SAMPLE SHOULD BE APPROVED BY A H.S.P BEFORE BULK PRODUCTION.
 ALT. MATL: STEEL 40, IS: 1570. AUTHORITY: CGA (HV) LETTER NO. 98704/04/D-CO-ORD/ALT.
 COM DATED: 03-05-2005

		EST. MASS 0.0014.	TO BE STAMPED OR MARKED WHERE INDICATED THUS # (LETTERS)
		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUT-SIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :- STEEL 40 GOST 1050-60.	USED ON :- A, 20 030 CB
ISSUE DATE	NATURE OF AMENDMENTS	CONTROLLER RATE OF INSPECTION (HEAVY VEHICLES) AVADI	
RN	SCALE - 5 : 1	TITLE :- SCREW	
V. Permit	DIMENSIONS IN mm.		
ID	TOLERANCE ON DIMNS UNLESS OTHERWISE STATED.	D S CAT NUMBER	
CD	ALL THREADS CONFORM TO		
PPD		DRAWING NUMBER A, 74 003	
ATE (B-2-198)			

SIZE A6

DRAWING NUMBER

A 74 006



- * DIMENSION FOR REFERENCES, OTHER DIMENSIONS ARE ENSURED BY TOOLS.
- REST OF TECHNICAL REQUIREMENTS AS PER SPECIFICATION TY 005 216-75

MASTER COPY

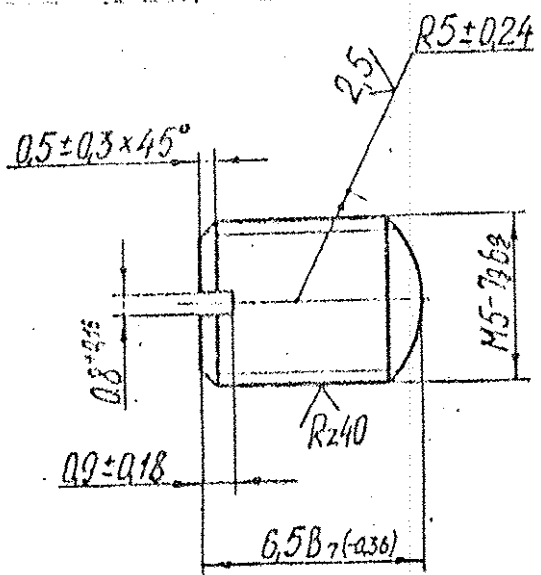
ALT. MATL :- NITRILE BA 70, BS: 2751-82
 AUTHORITY :- 98704/04/1D-CO-DRD/ALT.COM,
 APPENDIX 'A' DATED 3/5/2005

PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

		EST. MASS 0.0005	TO BE STAMPED OR MARKED WHERE INDICATED THUS (LETTERS)
		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUTSIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :- PLATE 254311-2 RUBBER HO-60-1 TY 005 216-75	USED ON :- A 20 000 CB
SUE IN	DATE	NATURE OF AMENDMENTS	CONTROLLER RATE OF INSPECTION (HEAVY VEHICLES) AVADI
<i>Ram</i>		SCALE - 1:1	
<i>Ram</i>		TOLERANCE ON DIMS UNLESS OTHERWISE STATED.	TITLE :- GASKET
<i>Ram</i>		ALL THREADS CONFORM TO	D S CAT NUMBER
<i>Ram</i>			DRAWING NUMBER A 74 006

DRAWING NUMBER
A 74 008

Rz80 ✓



ALT. MATL :- STEEL 40, IS: 1570
 AUTHORITY :- CBA (HV) LETTER NO. 98704/04/ID-
 CO-ORD/ALT. COM, APPENDIX 'A'
 DATE 03/05/2005.

- HRC 32, ..., 37.
- SHIFT OF SLOT RELATIVE TO SCREW AXIS SHOULD NOT EXCEED 0.3mm.
- COATING Cd9.

PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

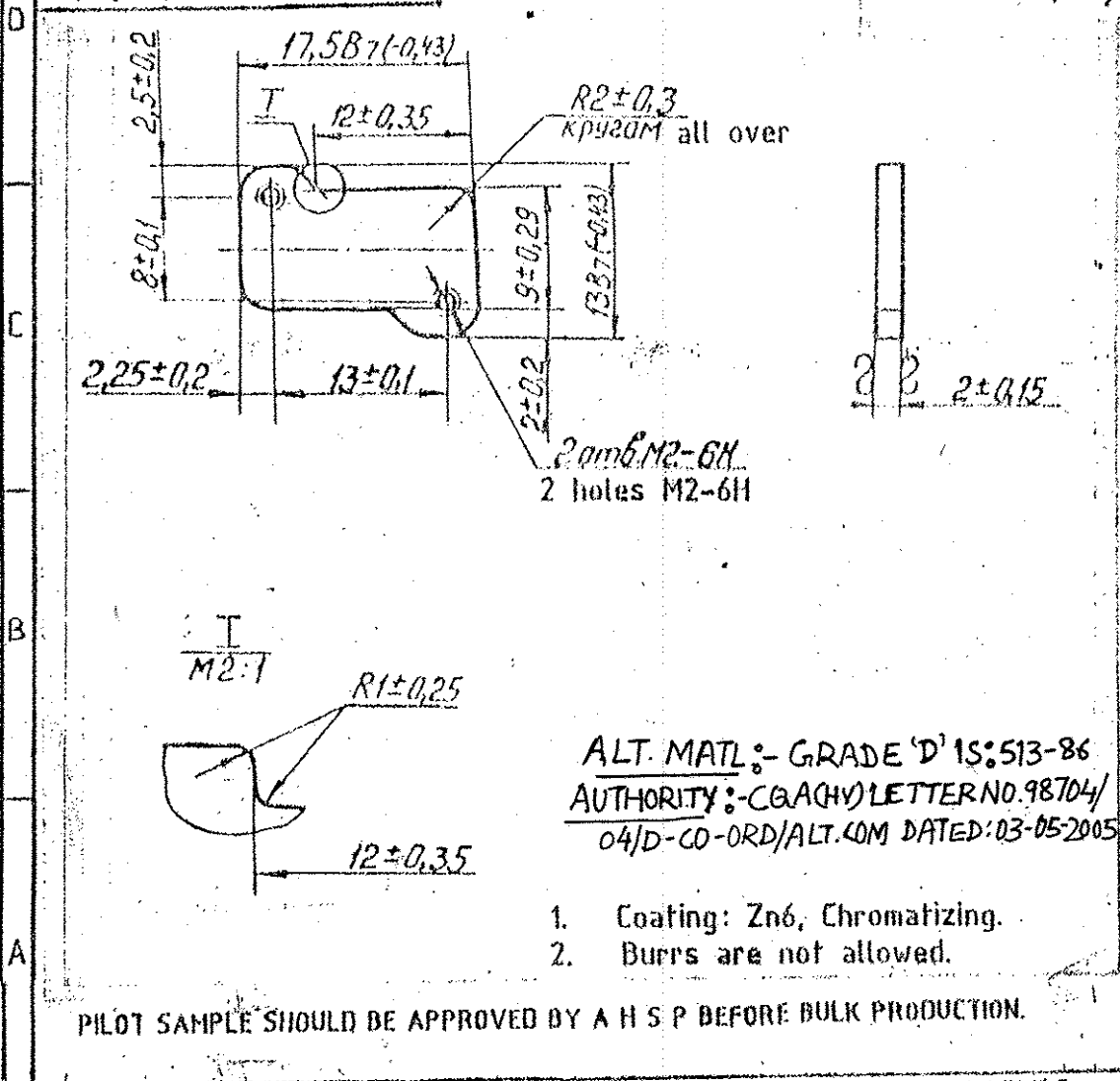
		EST. MASS 1g	TO BE STAMPED OR MARKED WHERE INDICATED THUS # LETTERS)
MASTER COPY		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUTSIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :- STEEL 40 GOST 1050-74.	USED ON :- A 20 000 CB
ISSUE DATE 19/02/2005	NATURE OF AMENDMENTS SCALE - 5 : 1	CONTROLLERATE OF INSPECTION (HEAVY VEHICLES) AVADI	
DESIGNED V. Ram	DIMENSIONS IN mm.	TITLE :- SCREW	
CHECKED V. Ram	TOLERANCE ON DIMS UNLESS OTHERWISE STATED.		
APPROVED 19/02/2005	ALL THREADS CONFORM TO	D S CAT NUMBER	DRAWING NUMBER A 74 008

SIZE A4

DRAWING NUMBER

D.74.014

▽3 (▽)



1. Coating: Zn6, Chromating.
2. Burrs are not allowed.

PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

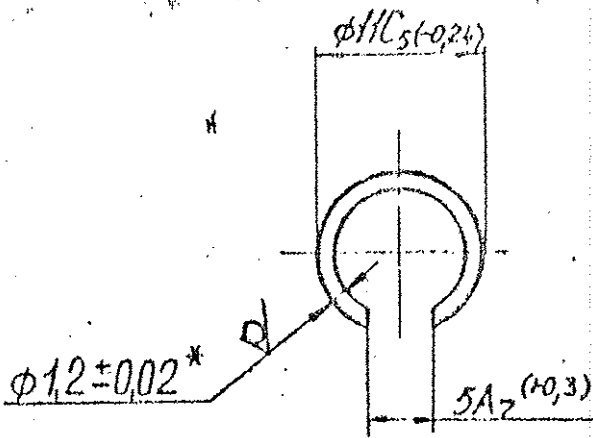
		EST. MASS 0.003	TO BE STAMPED OR MARKED WHERE INDICATED THUS (LETTERS)
MASTER COPY		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUTSIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL :- SHEET B-2 GOST 19904-74 4-110 GOST 16523-70	USED ON :- A.20 000 CB
ISSUE	DATE	NATURE OF AMENDMENTS	
IN		SCALE - 2 : 1	
NO		DIMENSIONS IN MM.	
CO		TOLERANCE ON DIMNS UNLESS OTHERWISE STATED.	
PPD		ALL THREADS CONFORM TO	
ATE	195 2/180	D S CAT NUMBER	DRAWING NUMBER D.74.014

SIZE A4

DRAWING NUMBER

Д74 021

Rz 30/



1. Low temperature tempering.
2. *Dimensions for references.
3. Non-flatness should not exceed 0.5mm.
4. Coating: Chemical oxidation, lacquer ГФ-95 GOST 8018-70.

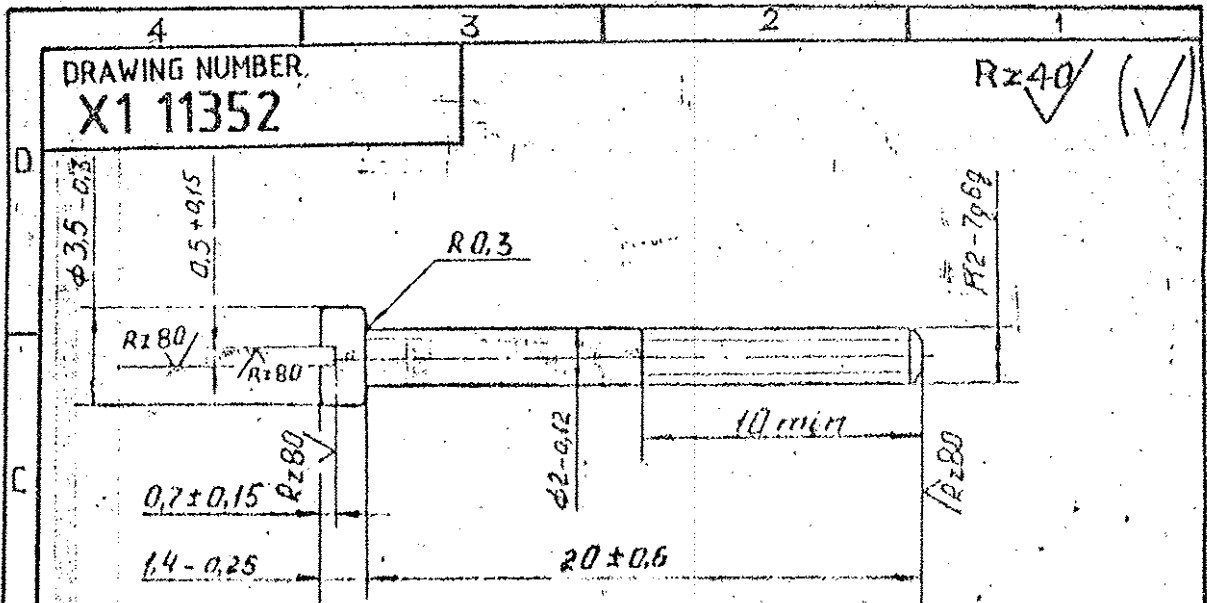
1. Низкая отпуск.

MASTER COPY

ALT. MATL. ° - GRADE '2' IS: 4454 (Part 1) - 1975
 AUTHORITY ° - 98704/04/ID-CO-ORD/ALT,
 APPENDIX 'A' DATED: 03/05/2005

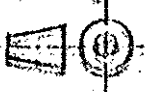
PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.

		EST. MASS 0.1g	TO BE STAMPED OR MARKED WHERE INDICATED (HUS 4) (LITERS)
		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUTSIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
		MATERIAL ° WIRE I-12 TY 144823-77.	USED ON ° Д,20 010 СБ
ISSUE DATE	NATURE OF AMENDMENTS	CONTROLLERATE OF INSPECTION (HEAVY VEHICLE): AVADH	
DRN V. Ram...	SCALE - 2:1	TITLE: RING	
CHD B. Shetty	DIMENSIONS IN mm.		
TEO V. Ram...	TOLERANCE ON DIMS UNLESS OTHERWISE STATED.	D S CAT N°	
APPD ...	ALL THREADS CONFORM TO		
DATE 18.2.1980		DRAWING NUMBER Д74 021	
SIZE A4			



1. Предельное отклонение от соосности осей шлица и шлица относительно оси стержня 0,15 мм.
2. Покрытие: Ц3-6, хромирование.
3. Технические требования по ГОСТ 1759-70.
 1. Limit deviation from alignment of head axis and slot relative to rod axis should be 0.15mm.
 2. Coating : Zn3-6, Chromating.
 3. Technical requirements as per GOST 1759-70.

PILOT SAMPLE SHOULD BE APPROVED BY A H S P BEFORE BULK PRODUCTION.
 ALT-MATL: STEEL OTOM 20 IS: 970-93. / En3A AUTHORITY: CGA (40) REF: NO. 98704/D
 -CO-ORD/ALT. COM. DATED: 03-05-2005

EST. MASS 0.404 g		TO BE STAMPED OR MARKED WHERE INDICATED THUS (LETTERS)	
ALTER COPY		ALL SHARP EDGES AND CORNERS TO BE REMOVED UNLESS OTHERWISE STATED MACHINED CORNERS TO HAVE R OUTSIDE R INSIDE EQUIVALENT CHAMFERS ARE PERMISSIBLE.	
MATERIAL :- STEEL A12 GOST 1414-75		USED ON :- A20 000 CB.	
ISSUE DATE	NATURE OF AMENDMENTS	CONTROLLER RATE OF INSPECTION (HEAVY VEHICLES) AVADI	
RN V. Ramani	SCALE - 4 : 1	 TITLE :- SCREW	
40 Blakach	DIMENSIONS IN mm.		
EN V. Ramani	TOLERANCE ON DIMNS UNLESS OTHERWISE STATED.	D B EAT NUMBER	
PRO S.P.	ALL THREADS CONFORM TO	DRAWING NUMBER X1 11352	
ATE 18.2.1917			

206-

1139

SENSOR A₁-20 SPECIFICATION

A 20.000 TY

VERIFIED
18 MAY 2007
JWM/STD-CELL

Translated by	Authenticated by	ARMoured VEHICLE PROJECT	
INSDOC	ORLOV	AVADI	
Date	Compiled by	SPECIFICATION No.	
10.11.85	<i>f. Mandala</i> 13/12	A 20.000 TY	
		Page No. 1 of 44	Approved by
			<i>K. Mandala</i> 16/12

①

These specifications cover sensing device A-20, hereinafter referred to as sensor, meant for commutation of automatic equipment electrical circuits.

Designation of the sensor while ordering: A-20, A20.000TY

1. TECHNICAL REQUIREMENTS

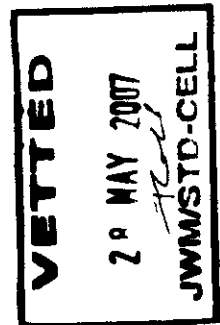
Sensor must conform to the requirements of these specifications, set of documents according to the specifications A.20.000 TY and OCT N3-1164-72.

All articles and materials, used for manufacturing of the sensor must conform to valid standards and specifications on them.

1.1 BASIC PARAMETERS AND DIMENSIONS

1.1.1 The sensor has the following main parameters.

- | | |
|---|------------------------|
| a) rated switching voltage | 27V DC; |
| b) commutated current | 0.5A; |
| c) operating condition | long-term; |
| d) connected ^{of connections} diagram ✓ | two-wire; |
| e) version | dust & splash proof. |
| f) working position | left; |
| g) Mass | not more than 0.35 kg. |



1.1.2 Overall dimensions as per the drg. A20.000TY-1.

1.2 Characteristics

1.2.1 Sensor must conform to the drawing A20.000TY-1 and set of documents as per specifications A20.000 w.r.t. overall and installation dimensions and exterior view..

A-20.000TY2

1.2.2 Sensor must withstand the action of vibrations at one of the frequencies in 20-25 Hz range with 2 g acceleration.

1.2.3 ^{Wiring} ~~Electrical installation~~ and assembly of the sensor must conform to schematic circuit diagram A 20,000 ③ assembly drawing A 20,000 (B) and ensure:

- a) stem working stroke till direct actuation of microswitch ^{contacts} controls - 1-2 mm (after guaranteed operating time 1-2.15 mm);
- b) force during stem working stroke not more than 3 kgf (at ambient air temperature of minus 50°C not more than 3.5 kgf);
- c) total stem travel (till stop) - 6 mm, min;
- d) force, required to achieve 6 mm stem travel - not more than 4 kgf (at minus 50°C ambient air temperature - not more than 4.5 kgf).

1.2.4 Insulation resistance between electrical circuits and casing and also between electrically disconnected circuits must be:

- a) under normal climatic conditions, practically in cold state not less than 20 Mohm;
- b) under high temperature conditions - not less than 5 Mohm;
- c) under high humidity conditions - not less than 1 Mohm.

1.2.5 Insulation between electrical circuits and casing and also between electrically disconnected circuits under normal climatic conditions must withstand:

25 V (effective value) 50 Hz, AC test voltage without breakdown or surface flashover.

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batch

- 1.2.6 Parts and assembly units of sensors of one ~~series~~ must be interchangeable.
- 1.2.7 Sensor must not have structural parts and assembly units with resonance frequencies upto 40 Hz.
- 1.2.8 Sensor must be fit for work and preserve its parameters under the conditions, specified in OCE 83-1164-72.
- 1.2.9 To meet guaranteed operating time, sensor must withstand 20000 ~~activations~~ *switchings* during bench-tests at a manufacturing plant.
- 1.2.10 Sensor service life must ~~amount to three~~ *be twice* of guaranteed operating time.
- 1.2.11 Sensor must not create interferences to radio-reception and (JS) Interphone system TNY operation.
- 1.2.12 Before acceptance tests, conduct sensor technological operation amounting to 700 ~~activations~~ *switchings* at 27V in bench-simulator circuit A20.000NM per the procedure on guaranteed operating test.

1.3 Completeness of set

1.3.1 The set consists of

- a) sensor A 20
- b) certificate



1.4 Marking

1.4.1 Sensor must be marked according to the set of documents *according* on specifications A20.000.

1.5 Packing and preservation.

Packing and preservation of sensor to be made according to the requirements ^{of} OCT B3- 1164-72 and valid packing drawing. Preservation of articles, supplied as spare parts is made according to the ^{of} requirements ~~for~~ OCT B3- 2881-84

2. ACCEPTANCE RULES

2.1 These specifications, OCT B3 -1164-72 and set of documents ^{according} ~~on~~ specification A20.000 are the main documents for manufacturing, testing and acceptance of the sensor.

2.2 All purchased articles must be checked by external acceptance section of ^{QTD} ~~QTD~~ before installation in sensor. Amount and procedure of ^{incoming inspection} ~~input control~~ is established in agreement with the customer's representative.

2.3 Sensor tests are divided into acceptance, periodic and type tests.

2.4 Each sensor is subjected to acceptance tests in amount and sequence according to table 1.

Sensors are offered for acceptance in batches of 80-100 pieces.

2.5 Periodic tests are conducted twice in a year on two specimen in amount and sequence as per table 1.

2.6 Type tests are conducted in order to check conformance of sensor to the requirements of these specifications; in case of basic changes in circuit, design or manufacturing technology of the sensor, which may effect on operational characteristics; in case of necessity to check service life of sensor and measures

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A20.000TY

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undertaken for ~~eliminating~~ ^{eliminating} of sensor defects and also on ~~initial~~ ^{initial} batch of ~~series~~ ^{lot} production.

Necessity of conducting type tests including service life tests is determined and agreed between manufacturer and customers representative in amount sufficient for checking the effectiveness of measures undertaken or service life, as per the agreed test programme, guided by the types of tests in table 1.

See page No. 38k³⁶ - Table 1 -



3. CHECKING METHODS

3.1 All tests are conducted under normal climatic conditions, except where climatic conditions are specifically stipulated.

Characteristics of normal climatic conditions:

- a) ambient air temperature $+25 \pm 10^{\circ}\text{C}$;
- b) air relative humidity- 45-80%;
- c) atmospheric pressure 630- 800 mm Hg. col.

Note: At a temperature higher than 30°C , relative humidity must not be higher than 70%.

Instruments must have a class of accuracy not less than 1.5.

3.2 Completeness, conformance to the requirements in drawings, quality of assembly, exterior finish, quality of soldering & absence of loose fixtures are checked visually; conformance of assembly to ~~drawing~~ ^{wiring diagram} ~~instrument~~ ^{instrument} installation and overall dimensions by ~~test tools~~ ^{test tools}.

3.3

Vibration-strength test at one frequency is conducted in order to expose rough technological defects, permitted in the manufacturing cycle of the sensor. Before testing, correctness of ~~electrical installation~~ ^{wiring} and assembly of sensor is checked. Sensor in disconnected state is rigidly fixed to bench platform in any position.

Test is conducted at one of the frequencies in the range of 20-25 Hz, with 2 g acceleration. Test duration is 30 min. Sensor is considered as withstood the test, if there are no mechanical damages and loosening of fixtures, and if ~~electrical~~ ^{wiring} assembly and working and full travel, forces conform to the requirements in cl.1.2.3 of these specifications.

3.4

Correctness of ~~electrical installation~~ ^{wiring} and assembly of sensor is checked by any method, which ensures checking of ~~electrical~~ ^{wiring} installation and assembly of sensor on conformance to circuit A20.000 B3 and drawing A20.000 C6 or as per the procedure, given below:

a) connect power supply PLUS to ~~contact~~ ^{terminal} 1, and MINUS through rheostat to ~~contact~~ ^{terminal} 2 of plug type connector; set 0.5±0.05A current with the help of rheostat and measure. Voltage drop across ~~contacts~~ ^{terminal} 1-2, whose magnitude must not exceed 185 mV; disconnect supply.

b) connect power supply PLUS to ~~contact~~ ^{terminal} 3, and MINUS through rheostat to ~~contact~~ ^{terminal} 4 of plug connector, drive-in sensor stem and set 0.5±0.05A current with the help of rheostat;

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measure voltage drop across ~~contacts~~ ^{terminals} 3-4, whose magnitude must not exceed 185 mV;

disconnect supply;

c) correctness of sensor assembly (forces of working & full travel) is checked on a special device according to the requirements of drq. A20.000 CB. Checking to be made in 2 positions of the drive: in case of projecting position of pusher by 3 mm from ~~starting plane~~ ^{joint face} and in case of sunk position of pusher by 1 mm from ~~starting plane~~ ^{joint face}.

Sensor is considered as withstood the test, if measured values of voltage drop do not exceed 185 mV and sensor conform to the requirements in cl.1.2.3 of these specifications.

Notes: 1. Connect power supply MINUS only ~~when rheostat~~ ^{when} rheostat, resistance value is maximum.

2. Procedure of checking ~~correctness of assembly~~ ^{wiring} and assembly of sensor, and also technological instructions must be agreed with the customer's representative.

3.5

Insulation resistance is tested with 550 V DC megohmmeter.

Insulation resistance is measured:

a) in free state of sensor stem, ^{across terminals} between ~~contacts~~ 2-3, 2-4 and 3-4 of plug connector and also ^{across} ~~between~~ sensor casing and each of the ^{terminal} ~~contacts~~ 2,3, & 4 of plug connector;

b) in pressed state of sensor stem, between ^{terminals} ~~contacts~~ 1-2 of plug connector.

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Sensor is considered as withstood the test, if the measured values of insulation resistance correspond to cl.1,2,4a of these specifications.

3.6 Insulation electrical strength is checked on a special high-voltage ~~equipment~~ ^{device} of not less than 0.5 kVA capacity by feeding test voltage for 1s.

Test voltage is applied between casing and each of the following plug connector ~~contacts~~ ^{terminals} successively: 2,3 and 4.

Insulation electrical strength between electrically disconnected circuits is tested between the following ~~contacts~~ ^{terminals} of plug connector: 2-3, 2-4 and 3-4; in case of sensor stem pressed till stop _g between contacts 1-2 of plug connector.

Sensor is considered as withstood the test, if there is no breakdown or surface flashover of insulation during checking.

Note: In case of subsequent checkings of sensor, before installation on the ~~machine~~ ^{article}, norm of test voltage is established as 80% of that envisaged by the requirements of these specifications.

3.7 In case of splash-proofability test, sensor in disconnected state is installed in the spray chamber in any position and subjected to the action of water jet directed from top with an intensity of 2-2.5 mm/min, uniformly sprayed by compressed air at 3.35kg/cm². Jet ~~sterilisation~~ ^{pressure spraying} must take place over the sensor at a height of not less than 100 mm.

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During test the sensor is gradually rotated by 360° around vertical axis. Test duration is 5 minutes.

At the end of the test, sensor is dried from outside and opened for inspection.

Sensor is considered as passed the test, if there is no water inside it.

3.8

In order to check the sensor on conformance to drawings and interchangeability as per the ~~requirements~~ ^{request} of customer's representative, one specimen from the accepted batch is disassembled.

In this case conformance of parts and assembly units to the requirements of design documents is checked.

In case there are no parts and assembly units on the assembly line, two sensors are disassembled.

Sensor is considered as passed the check on interchangeability, if parts and assembly units conform to drawings and after their replacement sensor will conform to the clauses of acceptance tests in these specifications.

Note: covers and other detachable parts are removed and replaced in the sensor.

3.9

Test on absence of resonance in structural parts is conducted during type tests after visual inspection & checking of ~~disassembly~~ ^{wiring} and assembly.

Sensor in non-working position with removed cover is rigidly fixed to vibration table.

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Test is conducted in three mutually perpendicular positions of the sensor (fig.1) successively as per the norms ^{of} table 2 with smooth change in vibration frequency in each sub-range.

- Fig. 1 - See page NO 38

- Table 2 - See page NO. 37.

Passage time through each subrange must be sufficient for exposure of resonance, but not less than 2 min. Absence of resonance in structural parts and assembly units of sensor is checked during the test with the help of instruments. Visual determination of resonance is permitted.

Sensor is considered as withstood the test, if there is no resonance of structural parts and assembly units in the range of specified frequencies or amplitude of vibrations of any part & assembly unit does not exceed twice of the amplitude of its fix point and if no mechanical damages are observed as result of visual inspection.

3.10

In case of moisture-resistance test, sensor in disconnected state with removed cover is located in hygostat with a relative humidity of 93-97% and 20-25°C temperature and kept in it for 5 days.

Increase in humidity upto 98% and temperature upto plus 35°C is permitted.

After withdrawal of sensor from hygostat but not later than 2-3 minutes, following is checked;

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- a) insulation resistance as per the procedure in cl.3.5 of these specifications;
- b) forces of working and full travels as per the procedure in cl. 3.4c of these specifications;
- c) sensor fitness for work by three time ^{switching} ~~activation~~ as per the condition of guaranteed operating time tests at 22+IV supply voltage;
- d) absence of corrosion;
- e) preservation of varnish and paint coatings.

After holding the sensor with removed cover for 12 hours under normal climatic conditions. insulation resistance and also insulation electrical strength are checked as per the procedures in cl.3.5 and 3.6 and forces of working and full travel as per the procedure in ⁺ cl.3.4c of these specifications. Sensor is considered as withstood the test, if it remains fit for work, insulation resistance conforms to the requirements ⁺ in cl. 1.2.4C of these specifications there is no separation of varnish and paint coatings and traces of corrosion are absent and after holding under normal climatic conditions, electrical strength and insulation resistance ^{values} conform to the requirements ⁺ in cl.1.2.5 and 1.2.4a respectively and forces of working and full travel forces conform to the requirements in cl.1.2.3 of these specifications.

3.11

In case of cold-resistance test, sensor in disconnected state is put into a cooling chamber in which temperature is

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reduced to minus 50°C and maintained with an accuracy of ±3°C. After achieving this temperature, sensor is kept in the chamber for 4 hours, then it is withdrawn from the chamber and not later than 2-3 minutes, sensor fitness for work is checked by three time ~~switching~~ ^{switching} at 22 V as per guaranteed operating time test condition and working and full travel forces are checked as per the procedure ^{at} in cl.3.4C of these specifications.

Sensor is considered as passed the test, if it remains fit for work and if ^{forces,} working and full travels ~~forces~~ conform to the requirements ^{at} in cl.1.2.3 of these specifications.

Note: It is permitted to ^{place} ~~locate~~ the sensor in cooling chamber in which temperature is already reduced to minus 50°C. In this case, sensor is kept for 5 hours in the chamber.

3.12

In case of heat-resistance test, temperature of plus 50°C is set in the heating chamber and maintained with an accuracy of ±3°C.

Sensor is connected to bench simulator circuit

kept in heating chamber in connected state at 29V for 4 hours, after that sensor is withdrawn from the heating chamber and not later than 3 minutes its fitness for work is checked by triple ^{switching} ~~switching~~ as per the guaranteed operating time test condition with 22 V power supply.

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Then the sensor is again put into a heating chamber in which temperature is set at plus 65°C and maintained with an accuracy of ±3°C and kept at this temperature for two hours.

At the end of the test, sensor is withdrawn from the chamber and within three minutes insulation resistance is checked as per procedure ^{at} in cl.3.5 and working and full travel forces as per the procedure ^{at} in cl. 3.4C of these specifications.

Sensor is considered as withstood the test, if ~~it~~ remains fit for work, insulation resistance conforms to the requirements ^{at} in cl.1.2 4b and if ^{forces,} working and full travel ~~forces~~ conforms to the requirements in cl.1.2.3 of these specifications.

3.13

In case of test on stability to the action of frost and dew, ~~so~~ the ~~sensor~~ ^{placed} sensor in disconnected state is located in cooling chamber and kept in it for 2 hours at a temperature of minus 20±5°C.

After this, the sensor is withdrawn from the chamber kept under normal climatic conditions and connected to bench circuit A20.000 PM ; in this case immediately after connection and after every 15 minutes ^{3 in} for 2 hours, and also under conditions of frost and dew formation sensor fitness for work is checked by triple ^{switching} ~~activation~~ at 22 V as per the procedure of ^{at} guarantee tests.

Sensor is considered as withstood the test, if it remains

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fit for work during stay under normal climatic conditions after withdrawal from the cooling chamber.

3.14

In case of test on the action of sea (salt) fog, sensor with closed covers is put into a chamber, in which temperature is set at 27-30°C and subjected to the action of salt fog.

Before ^{placing} ~~the sensor~~ in the chamber, absence of damaged varnish-and-paint coatings is checked by visual inspection.

Sensor is located in the chamber in such a way that solution splashes and also drops from ceiling, walls and suspension system do not fall on the sensor during test.

Fog is formed by spraying with centrifugal aerosol equipment or pulverizer of salt solution, which is prepared by dissolving 33±3 g/l of sodium chloride in distilled water (GOST 4233-77). Fog must have particle size of 4-10 μ (95% drops) and water content of 2-3 g/m³.

Solution is sprayed for 15 minutes after every 45 minutes.

Total test duration is 2 days. Test duration is counted from the time of first solution spray.

At the end of the test, sensor is washed with ^{wed} ~~tap~~ water, wetted in distilled water, after that it is dried for 1 hour at a temperature of +55±2°C followed by cooling and visually inspected.

Sensor is considered as withstood the test, if no traces of corrosion and damage to varnish-and-paint coatings is observed.

3.15

In case of test on ^{resistance} ~~stability~~ to cyclic changes in temperature.

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sensor in disconnected state is subjected to the action of three cycles of changes in temperature continuously one after another.

Each cycle is conducted in the following sequence:

Sensor is put into cooling chamber, in which temperature is already reduced to minus 50°C and kept at this temperature for 4 hours.

From the cooling chamber, sensor is immediately transferred to heating chamber at +65°C and kept at this temperature for 4 hrs.

Holding time in heating and cooling chamber is counted from the time of achieving the specified air temperature of in chamber after insertion of the sensor.

At the end of the last cycle, sensor is withdrawn from heating chamber and kept under normal climatic conditions for 4 hours.

After that, sensor is visually inspected, ^{forces,} working and full travel ~~forces~~ are checked as per the procedure in cl. 3.4C of these specifications and sensor fitness for work is checked by triple ^{switching} ~~operation~~ at 22 V as per guaranteed operating time test conditions.

Sensor is considered as withstood the test, if it remains fit for work, and ^{forces,} working and full travel ~~forces~~ conforms to the requirements ^{of} in cl. 1.2.1 and 1.2.3 of these specifications.

Note: It is permitted to conduct test on ^{resistance} ~~stability~~ to cyclic changes in temperature in one chamber with rate of change in temperature not less than 0.5°C per minute.

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2.16

Vibration-resistance test is conducted on the table with single-component vertical or horizontal vibration successively in three mutually perpendicular positions of sensor, given in cl.3.9 of these specifications. Sensor is visually inspected before the test.

Sensor is rigidly fixed to the table and connected to the bench. A 20.000 HM, then 22V power supply is fed to the bench, lamp $\Lambda 1$ on bench glows and sensor is subjected to vibrations according to the standards, given in table 3.

- Table 3 - See page NO. 37.

Test is conducted with smooth change in frequency in each sub-range in one direction from lower frequency to upper or viceversa, in this case absence of false actuations is checked (lamp $\Lambda 1$ must not extinguish and lamp $\Lambda 2$ must not glow). Passage time through each sub-range must not be less than 2 minutes.

At the end of the test, sensor is visually inspected and fitness for work is checked by triple ~~switching~~ ^{switching} at 22 V as per the procedure on guaranteed operating time tests, ^{forces,} working and full travel ~~forces~~ are checked as per the procedure in cl. 3.4C of these specifications.

Sensor is considered as withstood the test, if mechanical damages and false actuations are absent and also if ^{forces,} working and full travel ~~forces~~ after vibrations conform to the requirements in cl.1.2.3 of these specifications.

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3.17

Impact-resistance test is conducted on impact stand.

Sensor is fixed rigidly to the stand and connected to functional check bench $\Delta 20.000 \text{ ПМ}$.

test is conducted successively in three mutually-perpendicular positions of the sensor, indicated in cl.3.9.

Sensor is visually inspected before the test, then 22 V power is supplied to the bench (lamp Л1 on bench glows) and sensor is subjected to the action of impact loads as per the norms given in table 4, in this case lamp Л1 must not extinguish and lamp Л2 must not glow.

- Table 4 - see page 38

At the end of the test sensor is visually inspected, its fitness for work is checked by triple ~~switching~~ ^{switching} at 22 V as per the procedure of guaranteed operating time test, and ^{forces,} working and full travels ~~forces~~ are checked as per the procedure in cl. 3.4C of these specifications.

Sensor is considered as withstood the test if mechanical damages and false actuations are absent, there are no loosening of fixtures and separation of coatings and also if sensor remains fit for work and if ^{forces,} working and full travels ~~forces~~ conform to the requirements in cl.1.2.3 of these specifications.

3.18

Vibration-strength test is conducted in disconnected state of sensor. It is visually inspected before the test.

Sensor is mounted on the table with single-component hori-

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